

MCS Version Notes:

- 4.05 July 19, 1999**
The Force and Mass items were reversed on the report. This was fixed.
- 4.04 July 6, 1999**
Added Ethernet to the list of controller selections; added the DMC-1800 and DMC-2100. Also, expanded the number of possible motors and amps.
- 4.03 February 5, 1999**
Added PCI bus to the list of controller selections; added the DMC-1802.
- 4.01 January 8, 1998**
Fixed a problem with converting torque units from large metric to small metric.
- 4.00 January 5, 1998**
New MCS designed for Win32 only.

- 3.02 March 26, 1996**
Fix inertia calculation problems.
- 3.01 February 29, 1996**
Remove some amplifiers from the amplifier catalog and replace with some new amplifiers. The amplifier catalog now has the following – MSA 12/80, ISA 8/160, ISA 15/160, MBA 6/60.
- 3.0 November 16, 1995**
Added a new report viewer and a new report format. Few memory problems have been fixed. A new file dialog window has replaced the old one.

- 2.09A September 27, 1995**
The file DPMI16BLOVL was missing from the distribution.
- 2.09 August 7, 1995**
This version adds in two new controllers - the DMC-1300, a four axis VME-Bus controller; and the DMC-1580, an 8 axis standalone controller. This version also has some minor changes on the printout. The values are now all printed as 4 significant digits. The motor also has the RMS torque displayed.
- 2.08 September 30, 1994**
Fixes windows version. Added 1080 and 1540.
- 2.07** Takes into account friction in the motor.
- 2.06** Allows user to calculate J by radius and mass.
- 2.05** This version now works correctly with Windows 3.1.
- 2.04** This version correctly prints out the friction produced by a linear load.
- 2.03** Allows leadscrew inertia calculation. Adds Load Inertia to Motor Inertia ratio to report and motor analysis window.
- 2.02** Adds written report. Makes units group selectable only.
- 2.01** Actual release. Has problems dealing with some memory managers.
- 2.00** Beta test.

1.13 Last version 1 release.